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CHAPTER 3. VECTOR ANALYSIS 3.1.3 Position and Distance

Vectors $z_2, y_2, z_1, y_1, x_1, x_2, x, y, R_1, R_2, z, P_1 = (x_1, y_1, z_1), P_2 =$

(x_2, y_2, z_2) O Figure 3-4 Distance vector $R_{12} = P_1P_2 = R_2 - R_1$,

where R_1 and R_2 are the position vectors of points P_1

and P_2 , respectively. Figure 3.3: The notion of the position vector to a point, P

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Elementary Vector Analysis, Prof. Dr. Nawazish Ali Shah
= \hat{v} = unit vector along dr Chapter IV: Vector Analysis In this chapter we shall be working primarily in the Cartesian system. Unless stated otherwise assume the system is Cartesian and any transformation, A , to another system is a rotation. Recall: in Cartesian systems, $g = 1$; $F_i = g_{ij} F_j = \delta_{ij} F_j$.

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